

# Delay-Tolerant Networking Modeling and Experimentation

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 Internet Society  
InterPlanetary  
Networking SIG

CONICET  


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DES  
SAARLANDES

**D3TN**  
COMMUNICATE BEYOND FRONTIERS

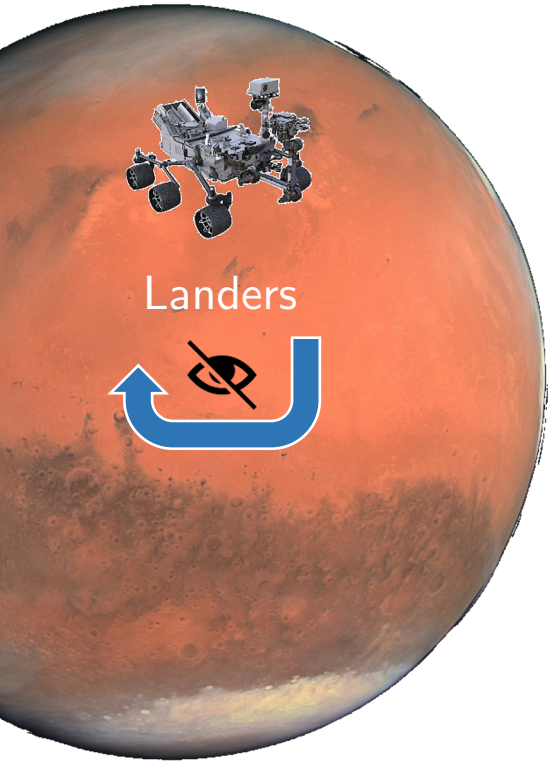
# Agenda

- **Motivation**
  - **Interplanetary Internet**
- Architecture
  - Delay-Tolerant Networking
- Modeling
  - Structures and Algorithms
- Experiments
  - ColdSun and RedMars

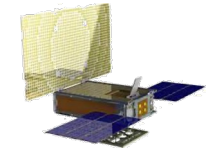


# Motivation

## Interplanetary Internet



Landers



CubeSats

Comms performance decreases as the square of the distance

GEO: ~40,000km

Mars: ~400,000,000km

100 million times weaker

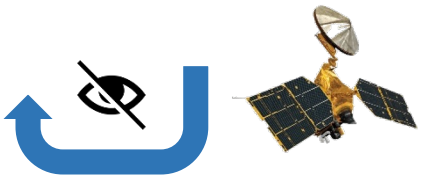
*min* 3.1 min

*avg* **12.5 min** *owlt*

*max* 22.4 min

Control Flow? DNS Lookup? Ping?

NASA's DSN



Orbiters

AU

	Mercury	Venus	Earth	Mars	Jupiter	Saturn	Uranus	Neptune
AU	0,38	0.72	1.00	1.52	5.21	9.54	19.18	30.11
Time	3 min	6 min	8 min	<b>12 min</b>	43 min	1h20	2h40	4h10

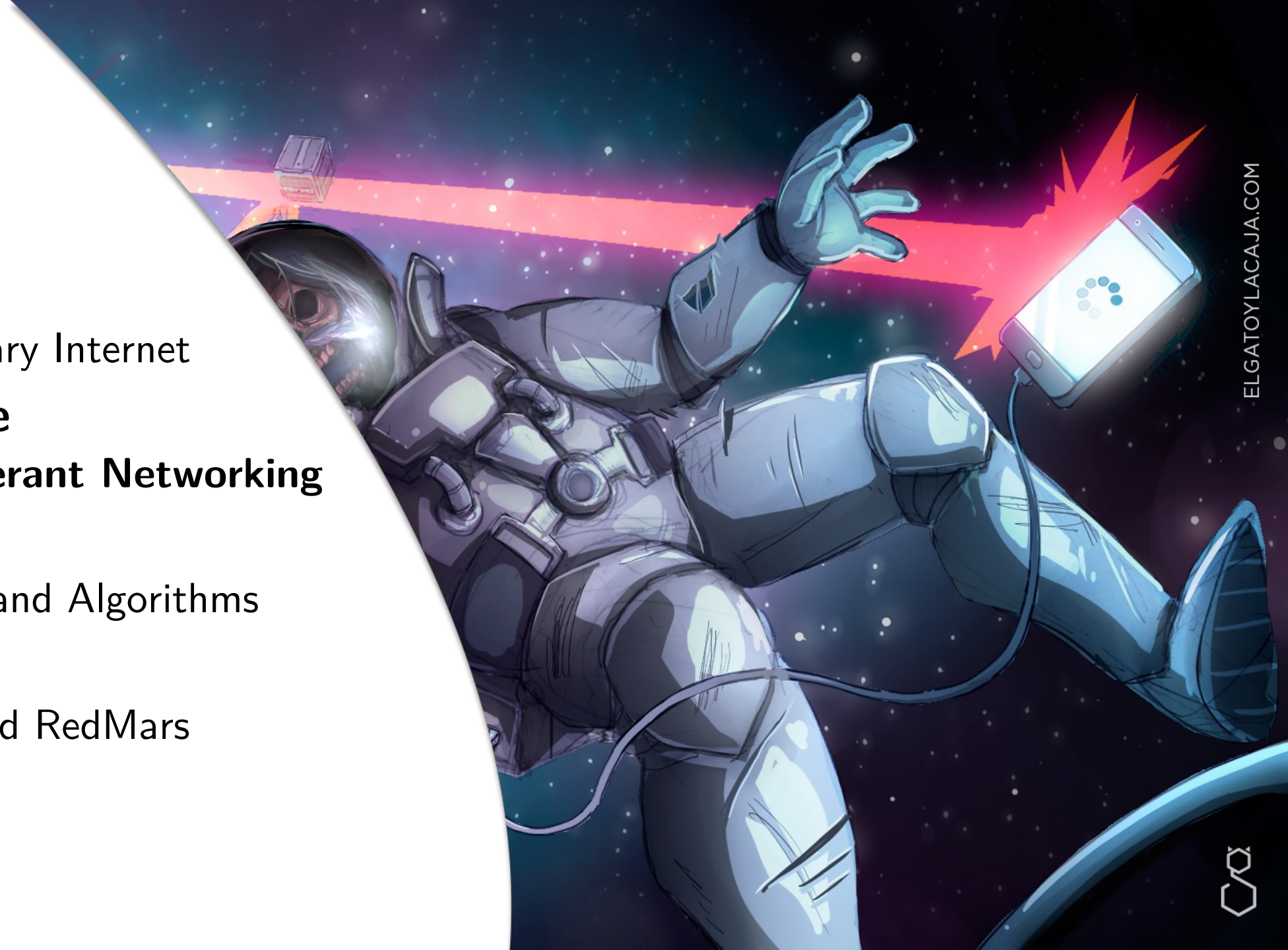
Voyager 1: 154 AU, 21:30 hrs.  
Voyager 2: 128 AU, 17:51 hrs.



[ipnsig.org](http://ipnsig.org)

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# Delay-Tolerant Networking

Data Handling Approach

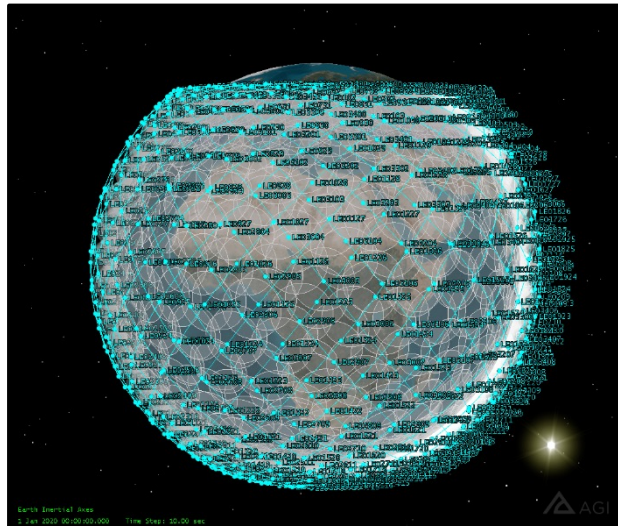
## Traditional Internet (TCP)

Instantaneous flow  
of information

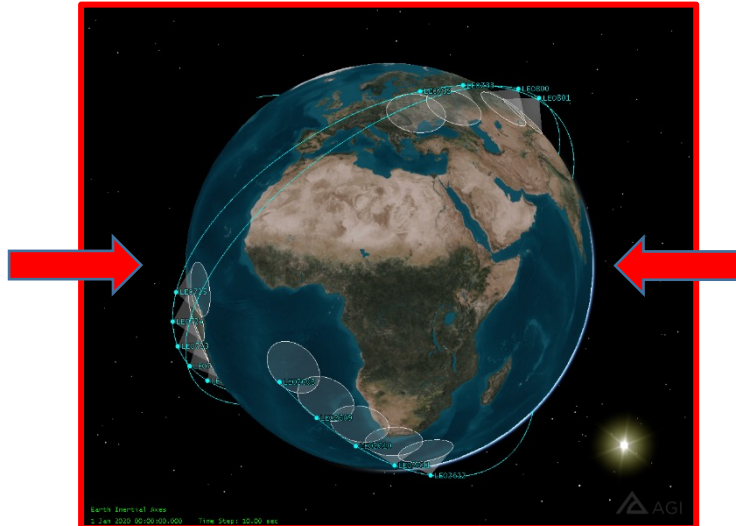
Telephony model

PEP's

Synchronous



Sparse Constellations  
Ring Road Networks

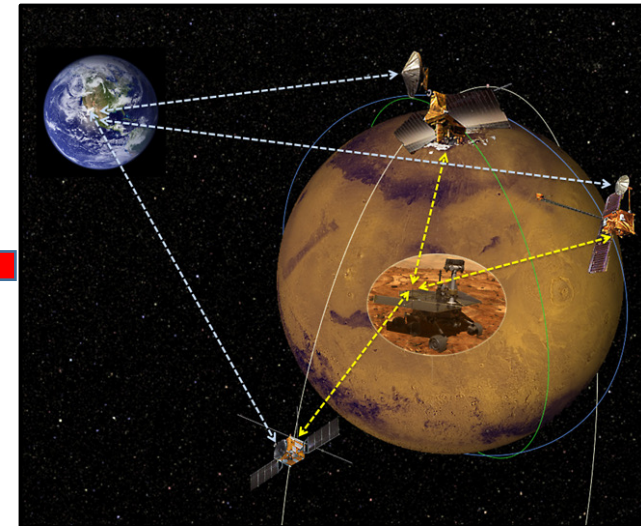


## Delay-Tolerant Networking (DTN)

Delay and disruptions  
Storage of data

Epistolary model

Asynchronous



# Delay-Tolerant Networking

## Architecture and Protocols

- Core Principles

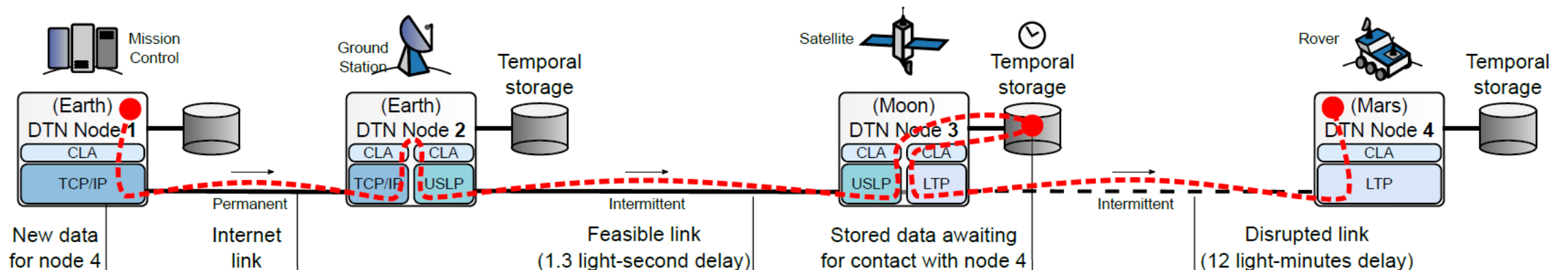
- Store-carry-and-forward
- Reduced end-to-end messaging

- DTN Architecture → Bundle Protocol

- Persistent storage (!= buffering)
- Bundle features: blocks, custody, fragmentation, deadline



- RFC 4838
- RFC 9171 (5050)
- CCSDS BP
- CCSDS BPSec
- CCSDS LTP
- CCSDS SABR



# Delay-Tolerant Networking

## Concept of Operation

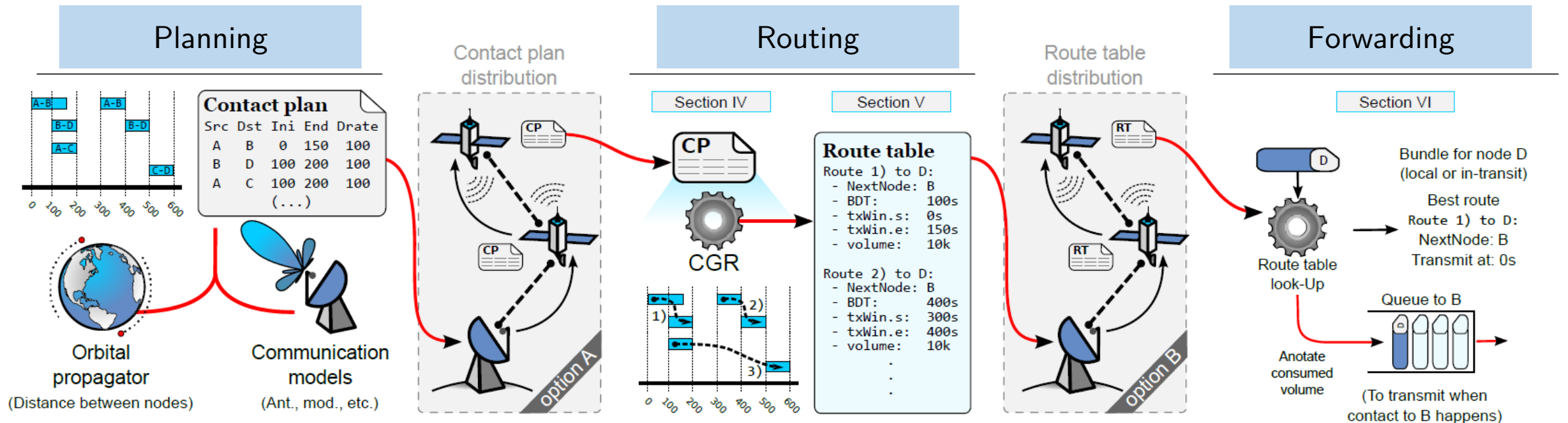
Strongly  
time-  
decoupled

**Planning:** computation of the *contact plan*

**Routing:** *path* computation from the contact plan

Path: *when*  
and to *which*  
neighbor

**Forwarding:** *path* selection and *queuing*





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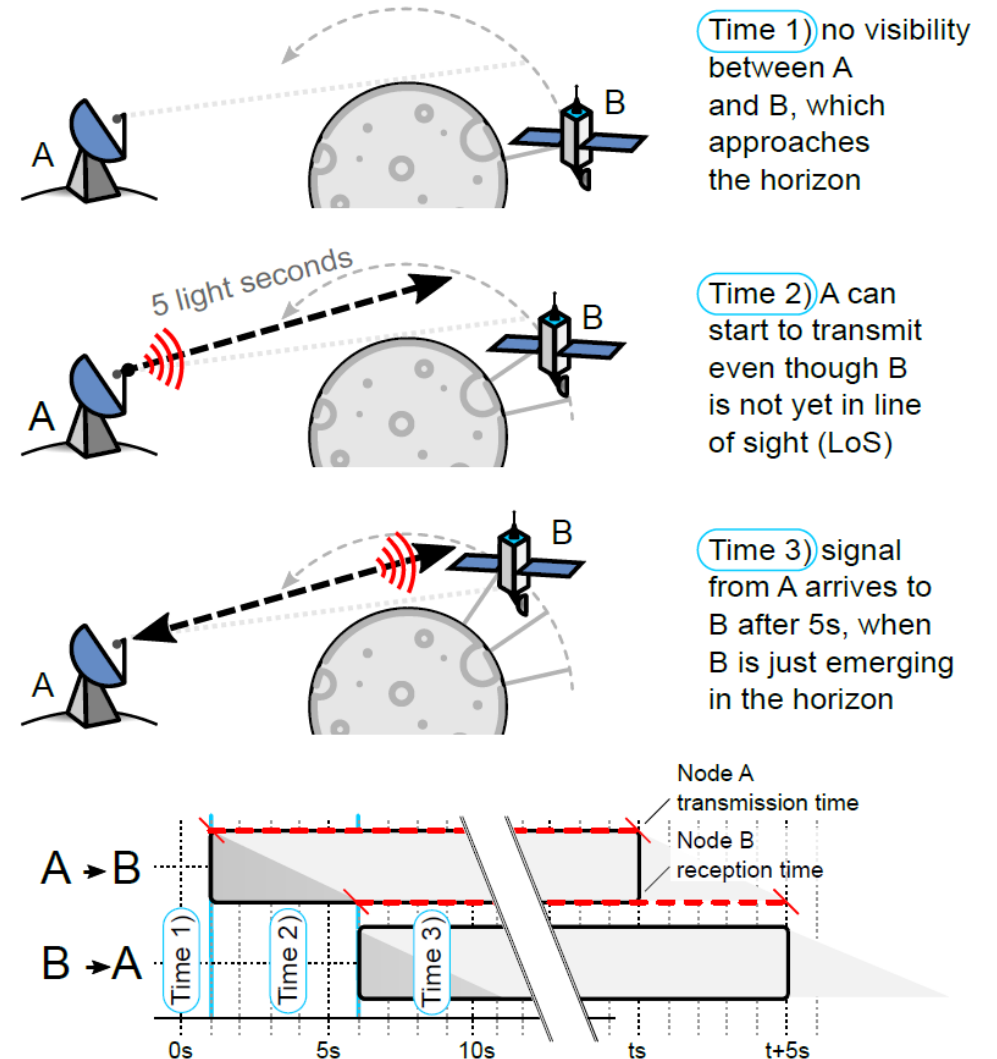


# Modeling

## Contact

- A contact  $C_{A,B}^{t1,t2}$ 
  - A time interval ( $t1; t2$ )
  - Data will be transmitted by node  $A$ , at a data rate  $R \rightarrow$  volume
  - That data will be received by node  $B$ , after one-way light time (*owlt*)
- Contacts are unidirectional
  - $\neq$  forward and return data rates
  - Due to *owlt*, the start time of a contact in one direction is typically **not** the same in the reverse channel

Possibly variable data rate

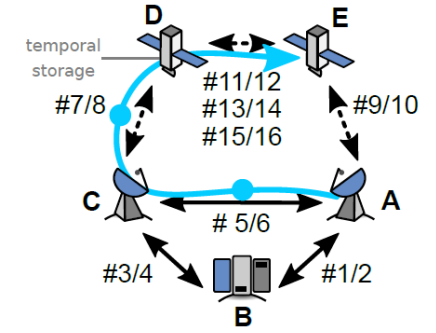


# Modeling

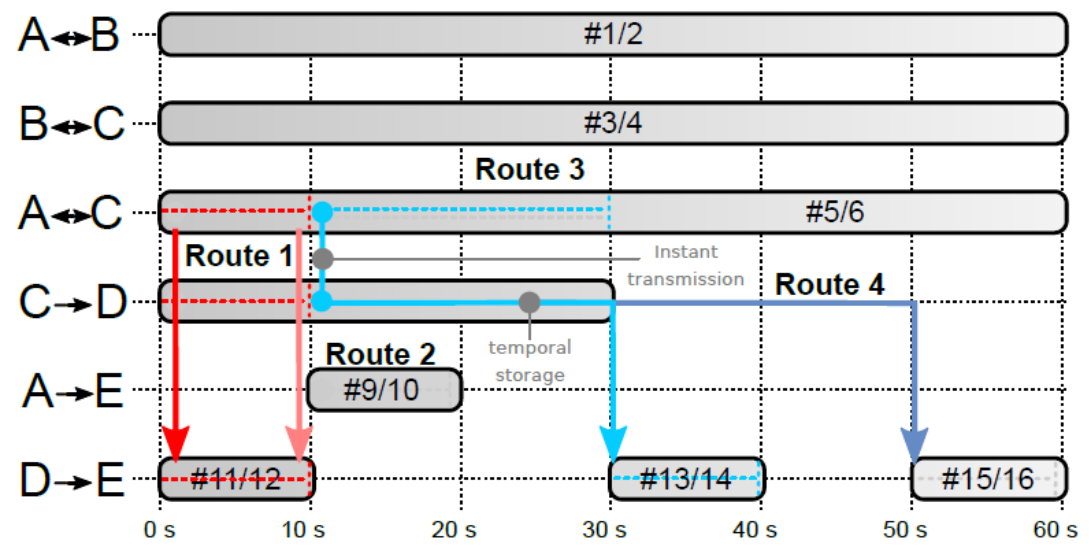
## Contact Plan

- **Contact plans** capture the time-evolving nature of the network

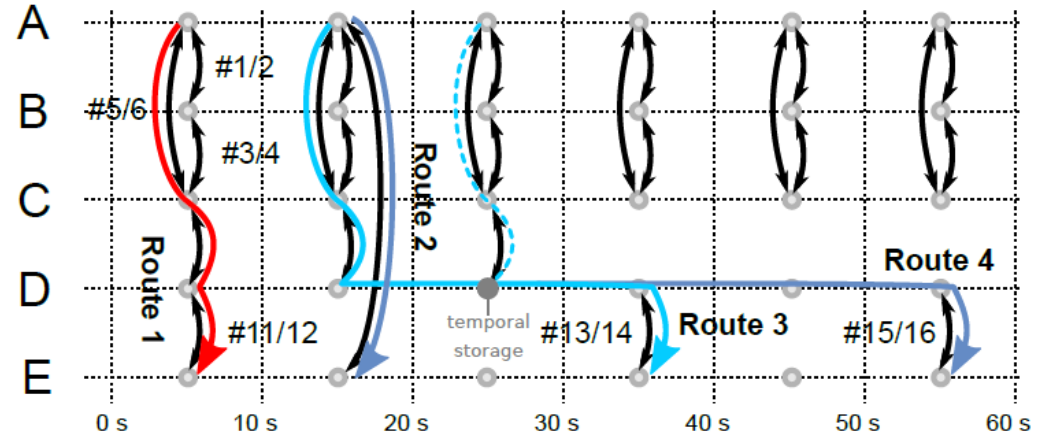
#	src	dst	st	end	rate	o
1/2	A	B	0	60	1	wl
3/4	B	C	0	60	1	t <sub>1</sub>
5/6	A	C	0	60	1	t <sub>1</sub>
7/8	C	D	0	30	1	1
9/10	A	E	10	20	1	1
11/12	D	E	0	10	1	1
13/14	D	E	30	40	1	1
15/16	D	E	50	60	1	1



Timeline view



Time Evolving Graph (TEG)



Scales poorly (nodes, contacts, time)

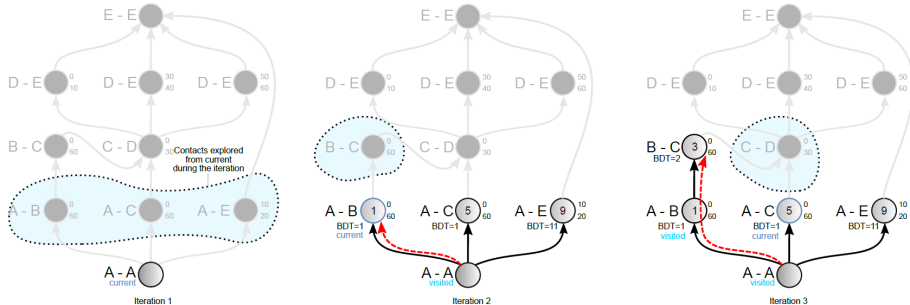
[1] Fraire, Juan A., Olivier De Jonckère, and Scott C. Burleigh. "Routing in the space internet: A contact graph routing tutorial." Journal of Network and Computer Applications 174 (2021): 102884.

# Modeling

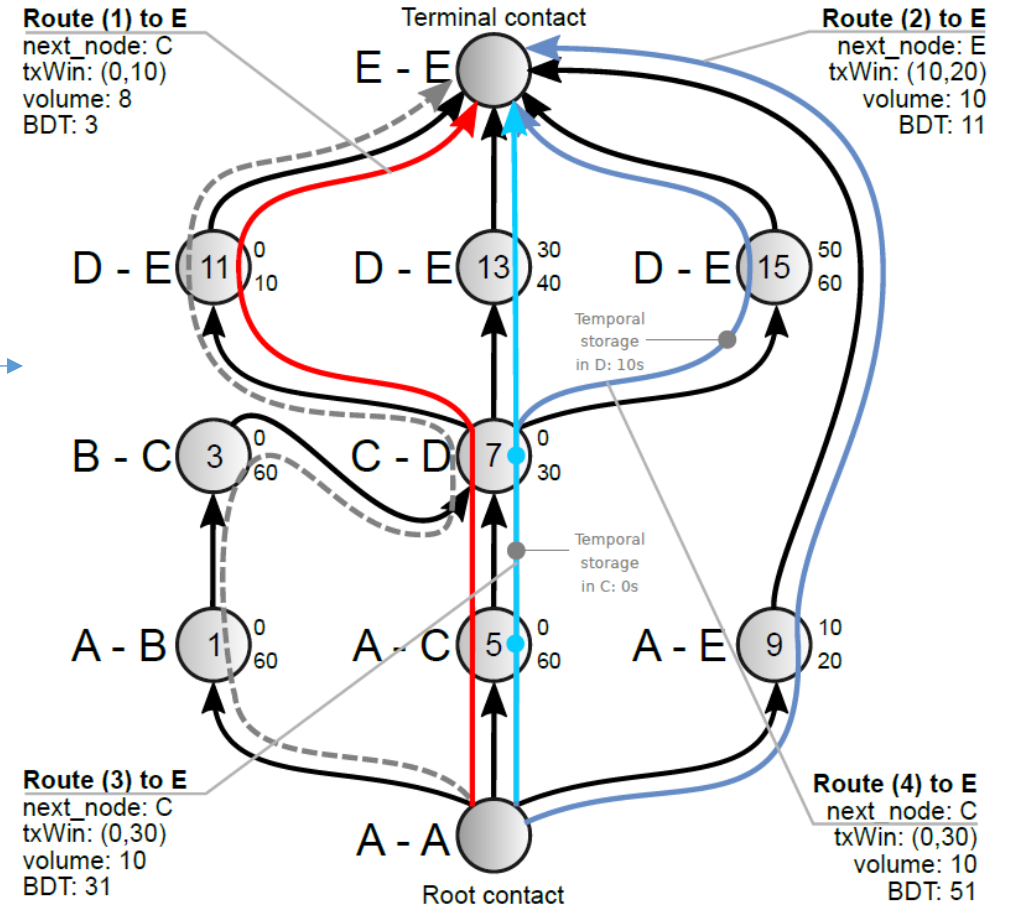
## Routing

- **Multi-Graph**
  - Nodes with multiple timed edges
    - Edges  $E$  are episodes of **contact**
    - Vertices  $V$  are episodes of **data retention**
- **Contact graph**
  - Destination node  $D$ , Source node  $S$ 
    - Edges  $E$  are episodes of **data retention**
    - Vertices  $V$  are episodes of **contact**

Shortest path algorithms



Directed acyclic graph  
 $CG_{DS} = (V; E)$

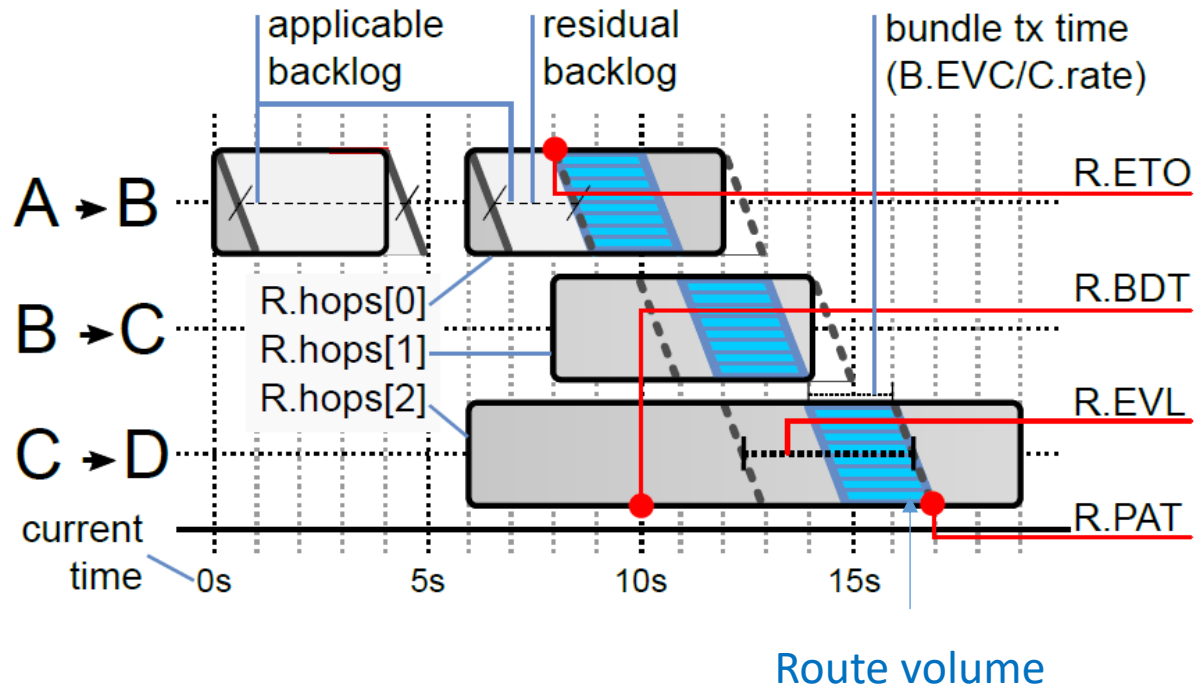


# Modeling

## Forwarding

- Candidate route list created

- Forwarding of local/in-transit bundle



- Candidate route metrics

- Best Delivery Time (BDT)
  - Deadline check
- Earliest tx opportunity (ETO)
  - Queue backlog
- Projected arrival time (PAT)
  - Transmission time  $\forall R.hops$
- Effective volume limit (EVL)
  - Lowest  $EVL \in R.hops$

Candidate list created on a per-bundle basis  
(uses bundle deadline and size)

# Modeling

## Congestion

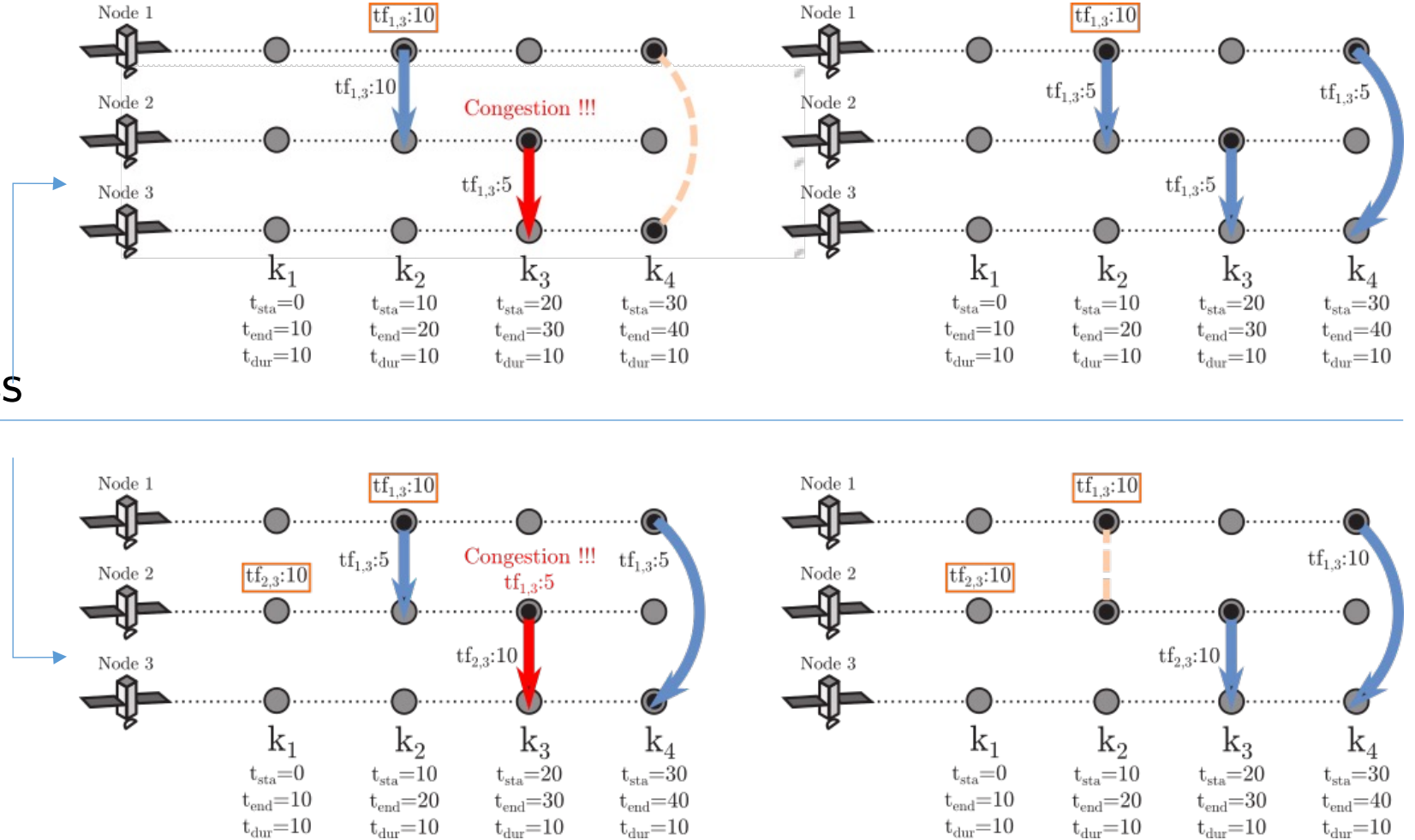
- *Reactive*

- Custody transfer
- Forecast warning

- *Proactive*

- **Topology awareness**
- **Traffic awareness**

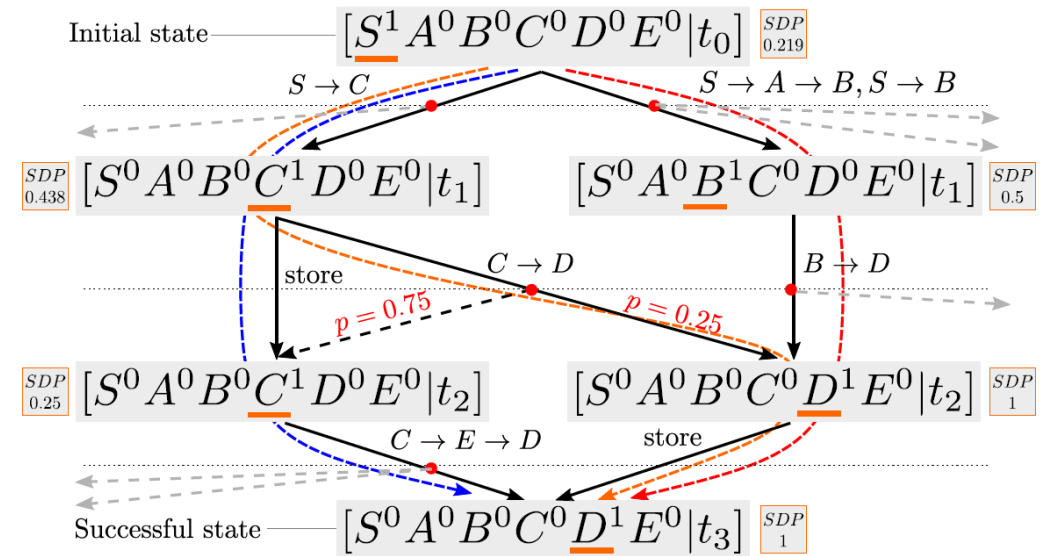
- Contact Plan Slicing [1]
- AI for traffic prediction



# Modeling

## Uncertainties

- Contacts → associated probability
  - Multi-copy forwarding
  - Timing information available from the contact plan
    - Traditional probabilistic routing, such as S&W or PRoPHET work with a simplified timing model (frequency)
- Markov Decision Process (MDP) → can provide optimal policies [1]
  - Require efficient search heuristics [2]
  - And AI learning (e.g., Q-Learning) [3]



Markov Decision Process (MDP)

[1] Raverta, Fernando D., et al. "Routing in delay-tolerant networks under uncertain contact plans." Ad Hoc Networks 123 (2021): 102663.

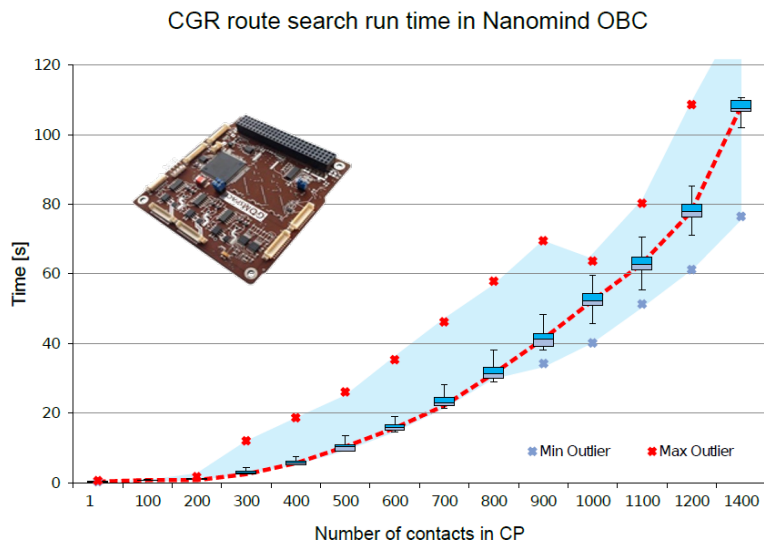
[2] D'argenio, Pedro R., et al. "Comparing Statistical and Analytical Routing Approaches for DTN" Quantitative Evaluation of Systems: 19th International Conference, QEST 2022, Warsaw, Poland, September 12–16, 2022, Proceedings. Cham: Springer International Publishing, 2022

[3] D'argenio, Pedro R., et al. "Comparing Statistical, Analytical, and Learning-Based Routing Approaches for DTNs" ACM Trans. on Modeling and Computer Simulation (TOMACS) (under review)

# Modeling

## Scalability

- Route computation effort scales with contact plan **size** and **duration**



CGR implementation in a CubeSat OBC [1]

### Alternatives

- Operate with **centralized** routing [2]
- Algorithm **optimization**
  - Spanning tree over multi-graphs (**SPSN**) [3]
- Topology **splitting**
  - Inter-Regional Routing (**IRR**) [4]
- Learning **models**
  - Graph Neural Networks (**GNN**) [5]
    - Goal: reduce on-board computing effort

[1] Vega, Blas F., and Juan A. Fraire. "Experimental Evaluation of On-Board Contact-Graph Routing Solutions for Future Nano-Satellite Constellations." (2020).

[2] Fraire, Juan A., and Elias L. Gasparini. "Centralized and decentralized routing solutions for present and future space information networks." IEEE Network 35.4 (2021): 110-117.

[3] De Jonckère, Olivier, and Juan A. Fraire. "A shortest-path tree approach for routing in space networks." China Communications 17.7 (2020): 52-66.

[4] Alesi, N. Hierarchical inter-regional routing algorithm for interplanetary networks. Master's thesis, School of Engineering and Architecture, Department of Computer Science and Engineering, Bologna, Italy, 2018.

[5] M. Olmedo, Juan A. Fraire "Routing in Scalable Delay-Tolerant Space Networks with Graph Neural Networks" International Conference on Embedded Wireless Systems and Networks (EWSN), 2023



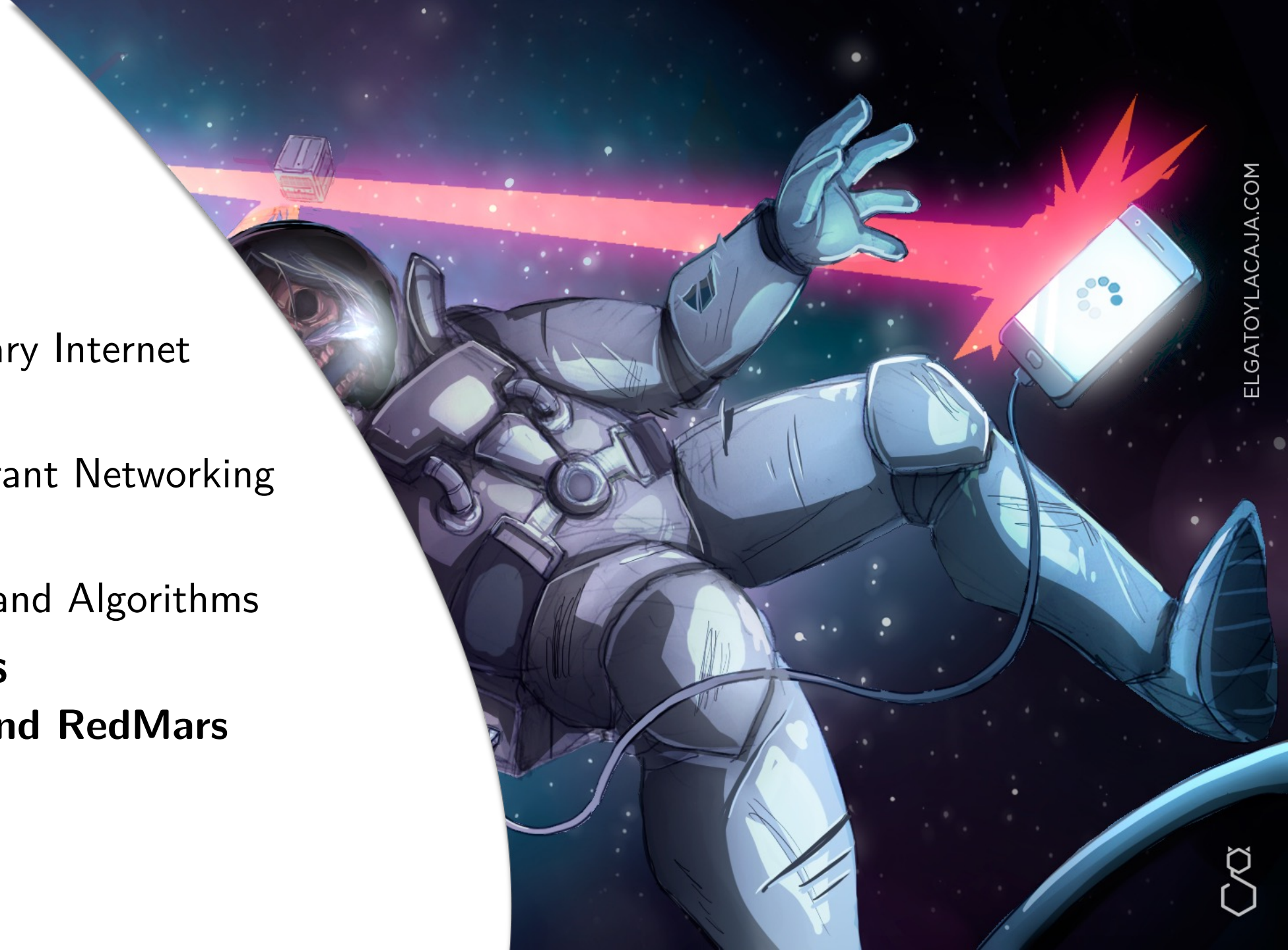
# Modeling

## Others

- Partial contact plan update (Rachel)
- AI for fragmentation determination (Rachel)

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  - **ColdSun and RedMars**

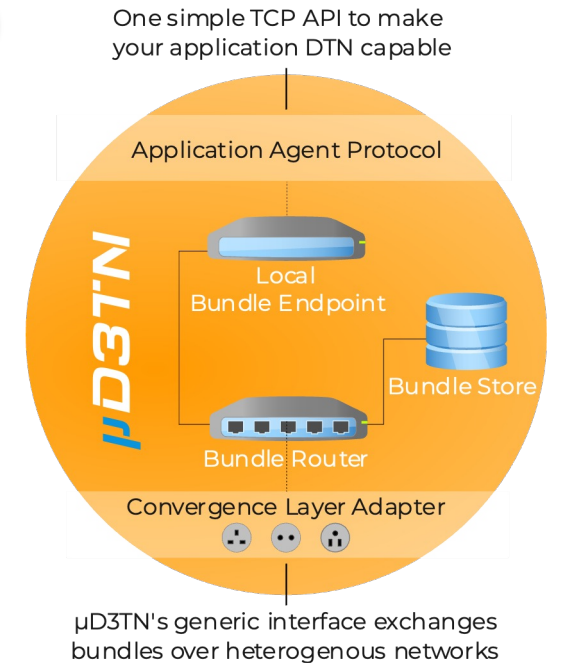


# Experiments

D3TN



- D3TN: Company located in Dresden  and Miami 
- Specialized in networking in *challenged environments*
  - Vehicular, underwater, and space
- Developer of  **$\mu$ D3TN** [1]
  - Open-source, lightweight DTN implementation
  - POSIX/Linux and STM32 microcontrollers (FreeRTOS)
  - First space-tested BPv7 implementation



[1] <https://d3tn.com/ud3tn.html> -  $\mu$ D3TN features

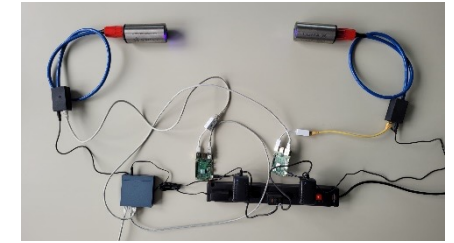
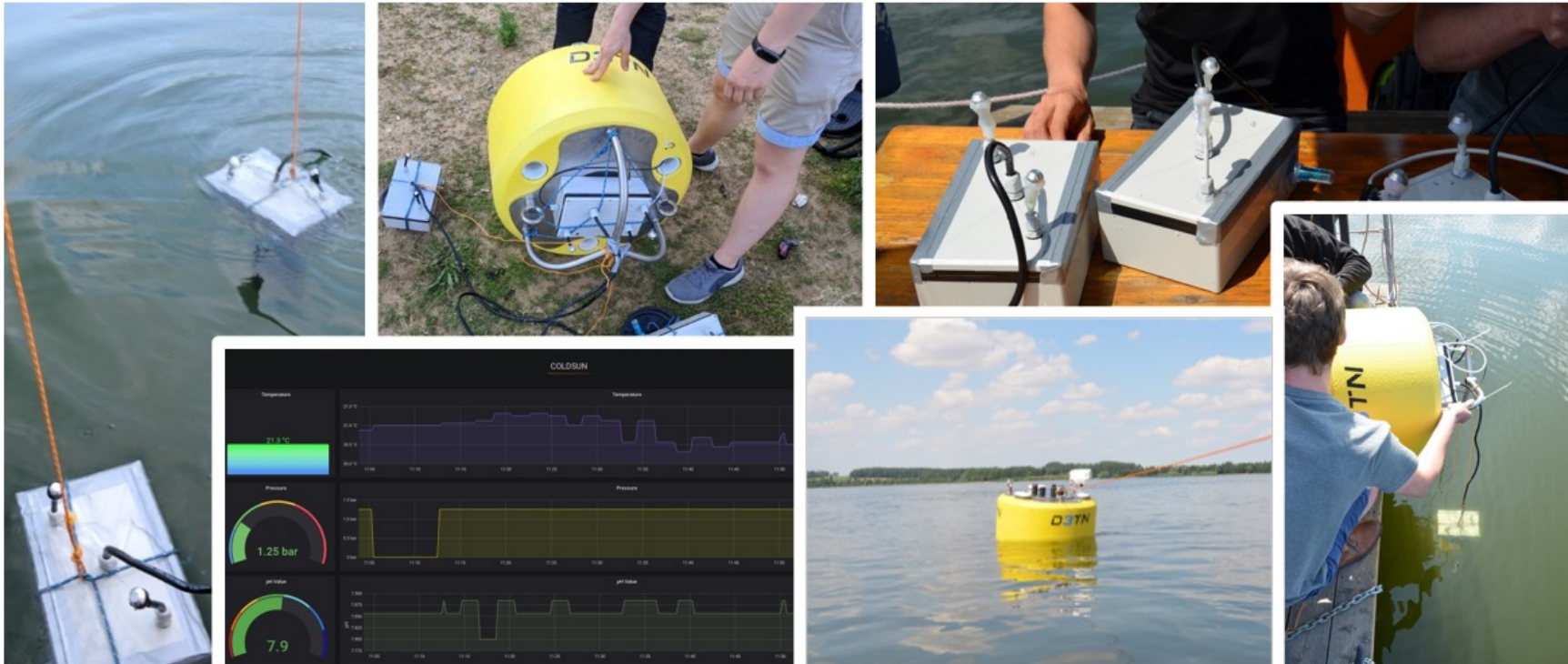
- **Northbound:** Straightforward application integration thanks to socket-based (TCP or Unix domain socket) Application Agent Protocol (AAP) interface
- **Core:** Full compatibility with ipn and dtn EID schemes, neighbor discovery (IPND), Bundle-in-Bundle Encapsulation (BIBE), modular opportunistic-deterministic DTN routing, and BPSec
- **Southbound:** Supports several Convergence Layer Adapters (CLA) such as CCSDS SPP, MTCP (draft v0), TCPCLv3 (RFC 7242), and TCPCLv4 (\*)

# Experiments

ColdSun

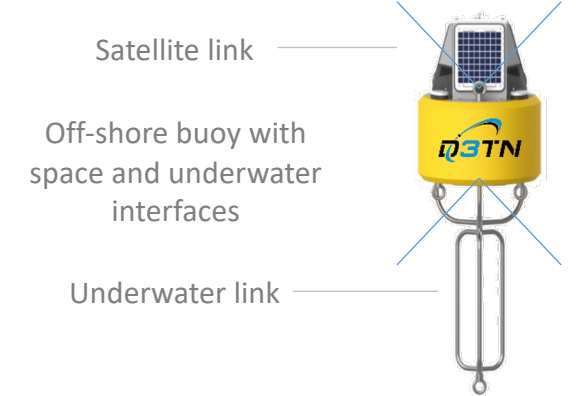


- *Underwater* to *Buoy* to *Satellite* to the *Internet*
  - End-to-end data transport with  $\mu$ D3TN ORBCOMM



Acoustic modems

Optical modems



AUV for dynamic data collection (data mule:  
higher throughput than direct link)

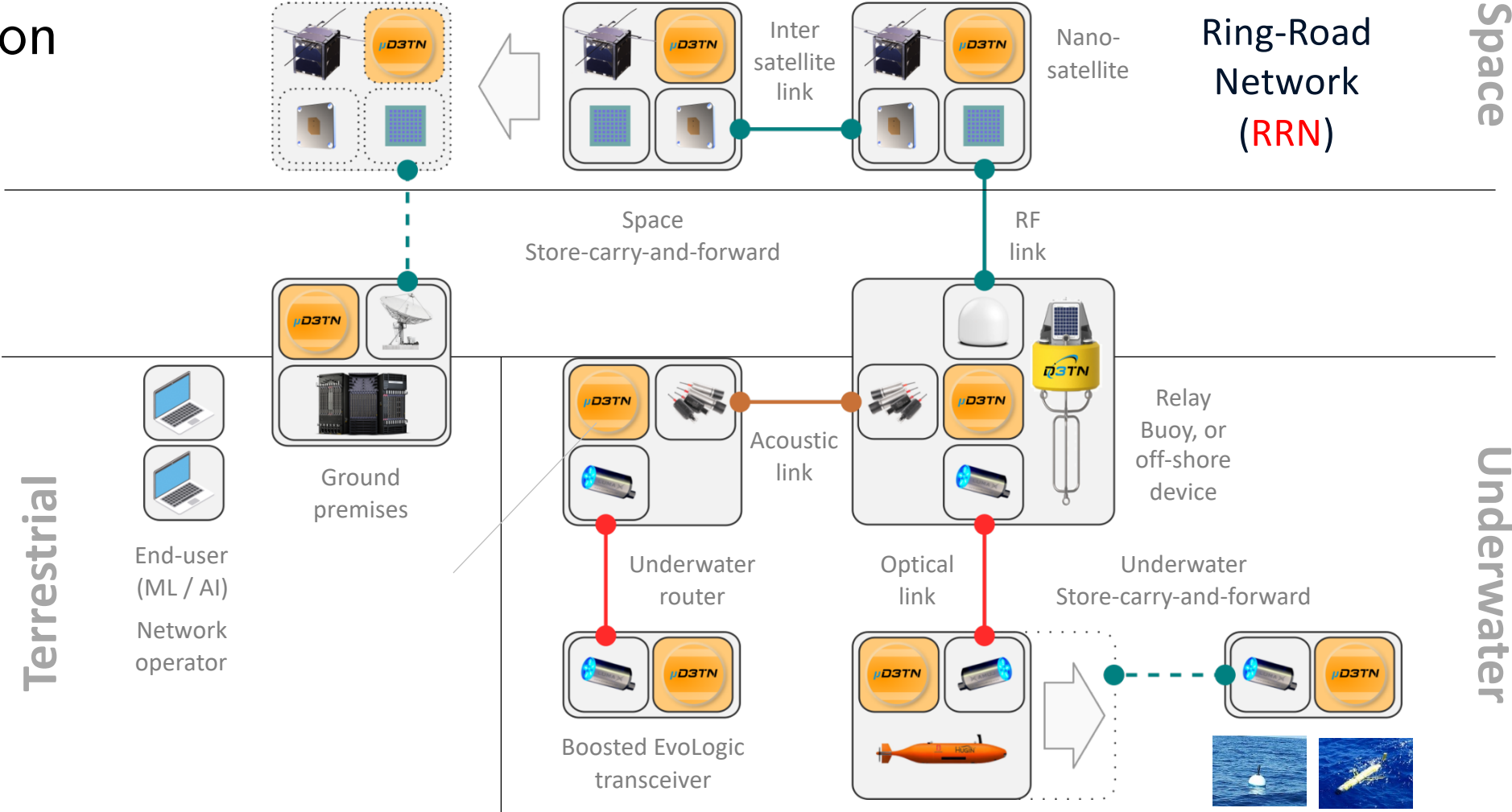


# Experiments

ColdSun



## ■ Vision

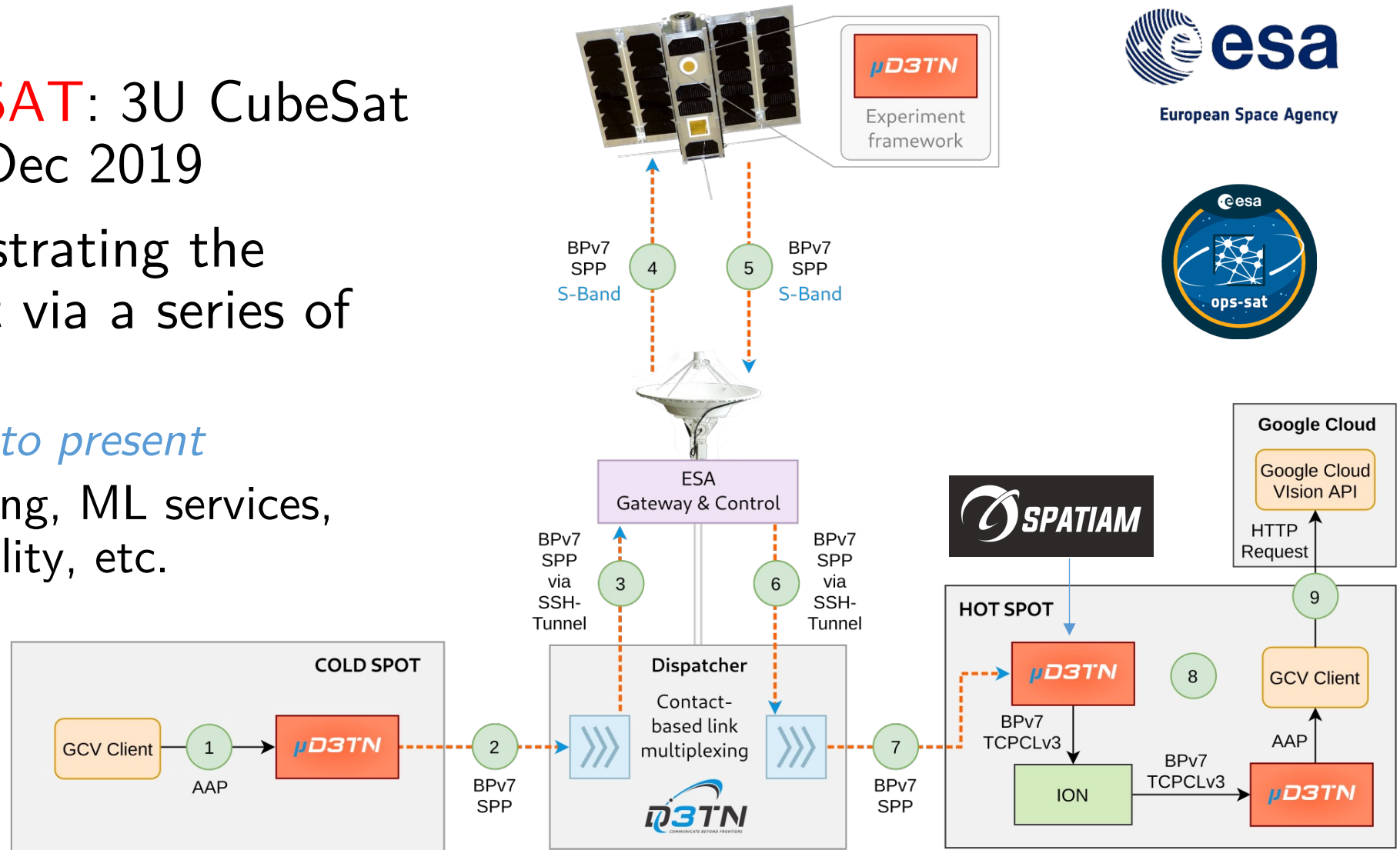


# Experiments

## OPS-SAT

- **ESA's OPS-SAT**: 3U CubeSat launched in Dec 2019
- **Goal**: demonstrating the RRN concept via a series of experiments
  - *From 2020 to present*
  - Web browsing, ML services, interoperability, etc.

$\mu$ D3TN on the ground and in space

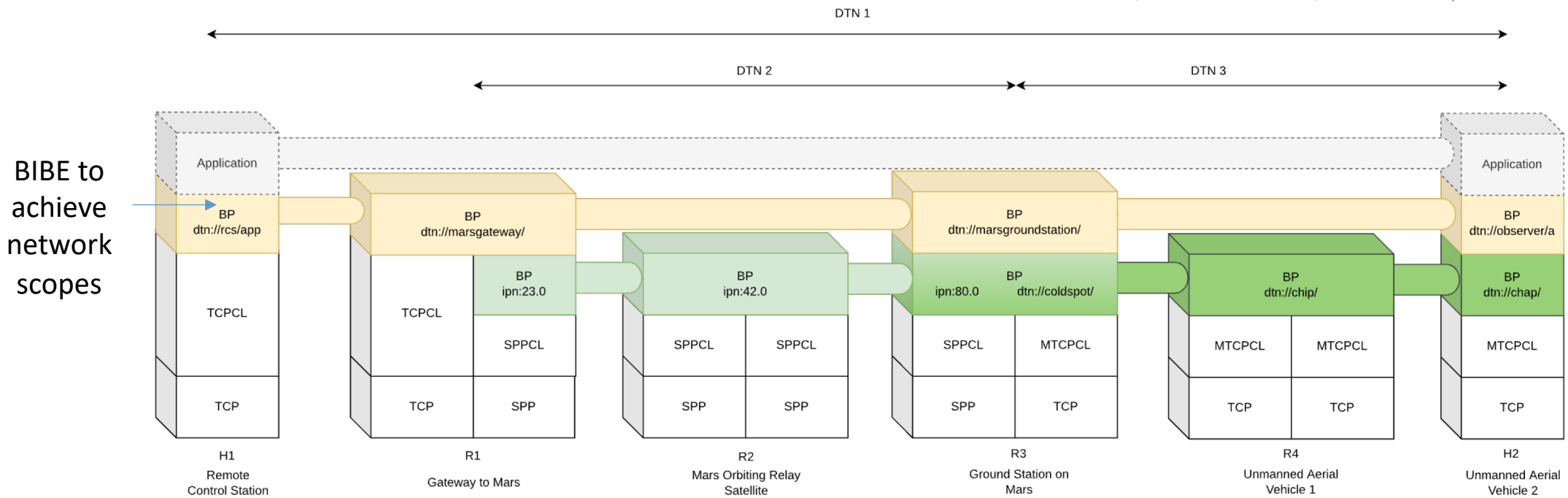
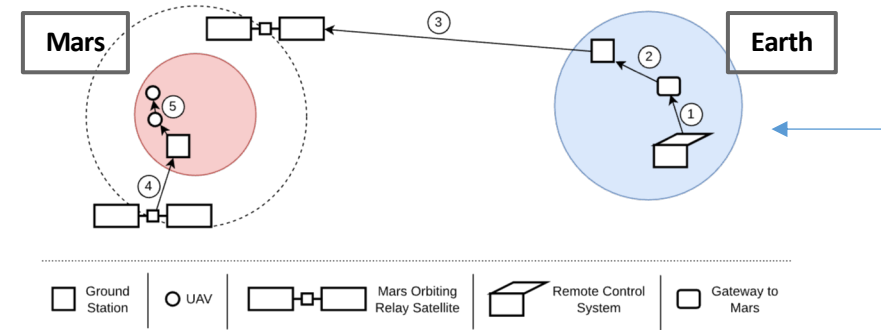


# Experiments

RedMars



- Adapt Recursive Inter-Network Architecture (**RINA**) [1] into DTN
  - Node mobility, function recursivity, etc.



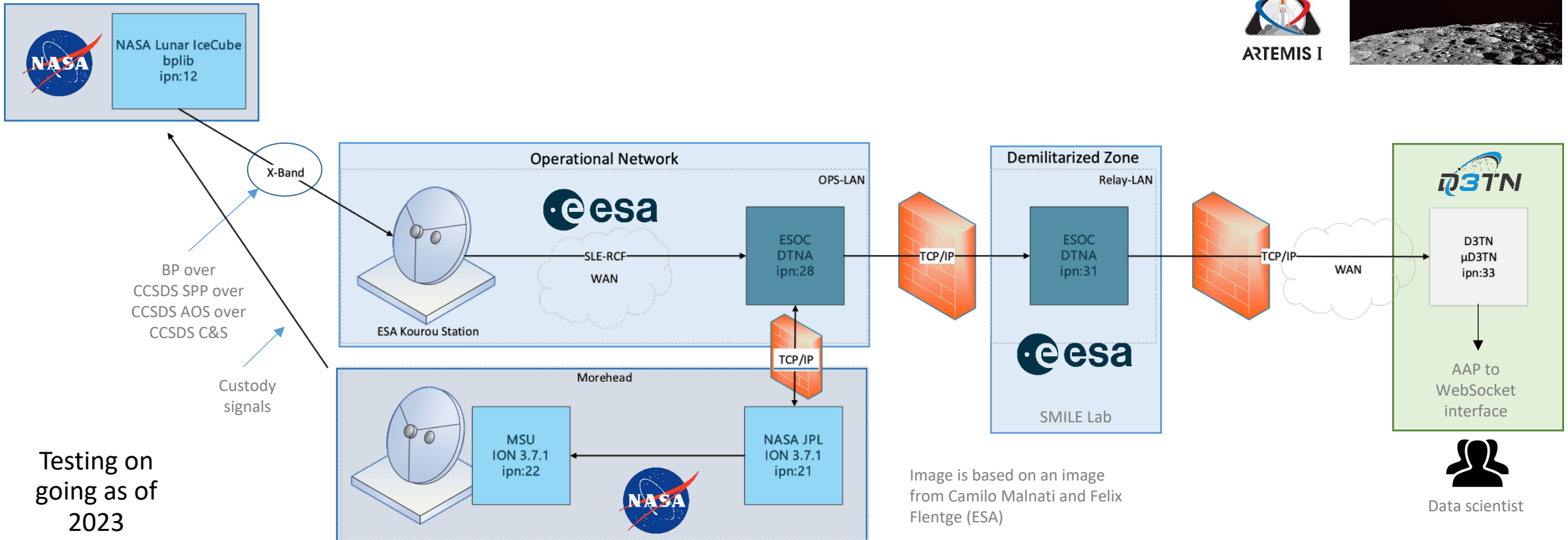
[1] Day, John. Patterns in network architecture. Pearson Education India, 2007.

# Experiments

RedMars



- Lunar IceCube [1] **cross-agency** data exchange via DTN



Testing on going as of 2023

Image is based on an image from Camilo Malnati and Felix Flentge (ESA)

[1] [https://en.wikipedia.org/wiki/Lunar\\_IceCube](https://en.wikipedia.org/wiki/Lunar_IceCube)



# Takeaways

Thanks for listening!

- **DTN brings time into the loop**
  - Adds a new dimension → asks for new modeling and experimental approaches
- **Modeling**
  - Data structures and algorithms are available, but flexibility/scalability are limited → Plenty of improvement and research opportunities ahead
- **Experimentation**
  - Stacks exist, but the reduced application scope hinders large-scale/long-term validation → Developing for terrestrial contexts might be the way
- **Artificial Intelligence**
  - Sometimes forced in networks where data is predictable and readily available
  - The challenge rests more in efficiently using the data (we have time)

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