

Implementing a Cognitive Routing Method for High-Rate Delay Tolerant Networking

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Introduction



- Space Communications and Delay-Tolerant Networking (DTN)
- Contact Graph Routing (CGR)
 - Standard DTN protocol
 - Limitations:
 - Network-wide congestion
 - Packet losses along the path
 - Metrics other than the bundle delivery time
- Cognitive Networking
 - Artificial intelligence and machine learning
 - Learning and prediction to optimize network performance

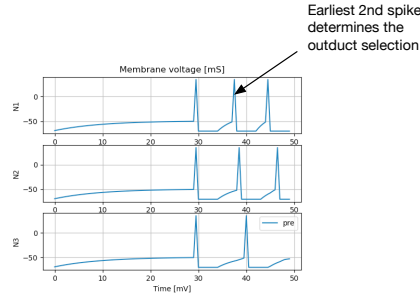
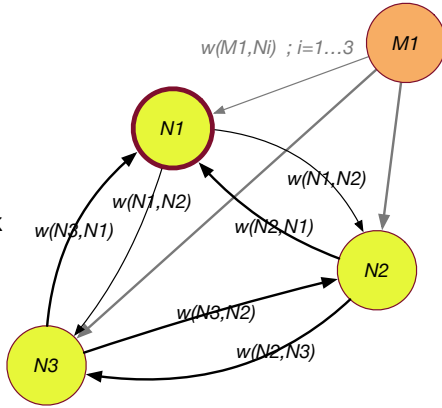
Cognitive Space Gateway (CSG)



- Reinforcement learning approach to the space bundle routing problem
- Spiking neural networks
- Design goals:
 - Dynamic
 - Distributed (autonomous operation)
 - (Near) real-time routing decisions
 - Multi-objective routing
- This study questions:
 - How to support multi-objective routing?
 - What is the realistic routing performance of the method?
 - Can the CSG method be improved?

CSG Approach: Optimal Routing Action

Spiking Neural Network (SNN) architecture defining the Cognitive Network Controller (CNC) for the CSG agent

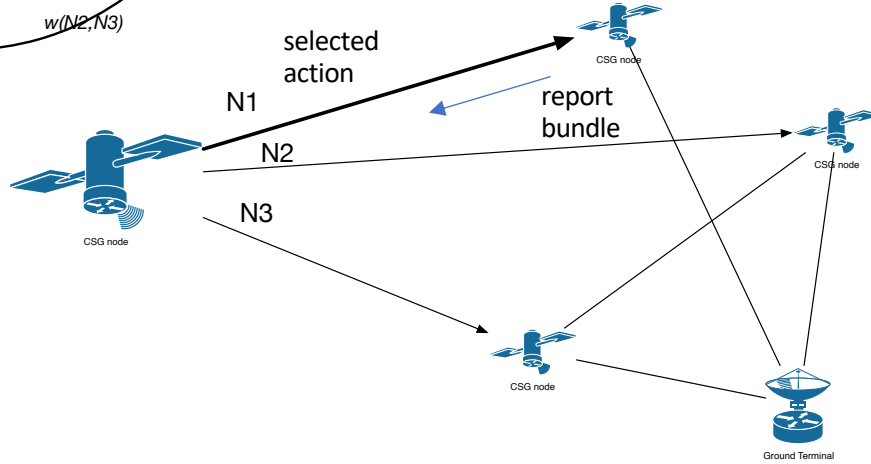


leaky integrate-and-fire neuron model

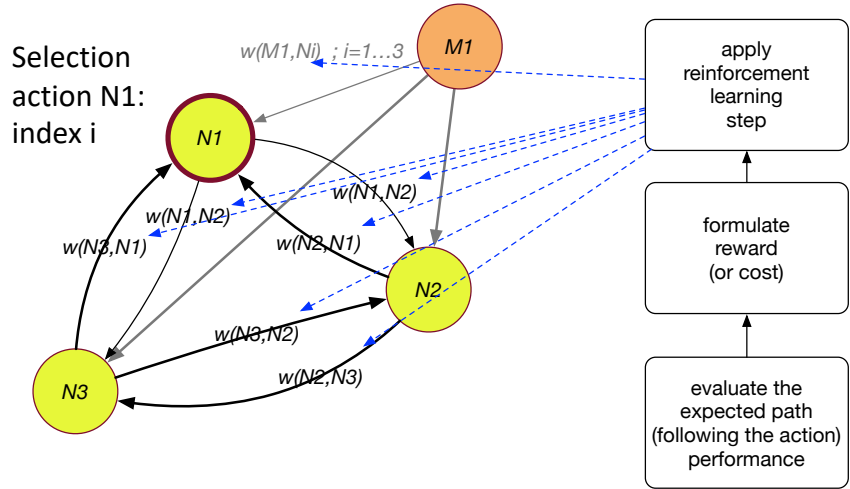
$$\tau \frac{d}{dt} u(t) = -u(t) + RI(t)$$

$$I(t) = i_e(t) + \sum_f \sum_j \sum_k w_{jk} i_{jk}^{(f)}(t)$$

CSG agent



CSG Approach: Learning & Exploration

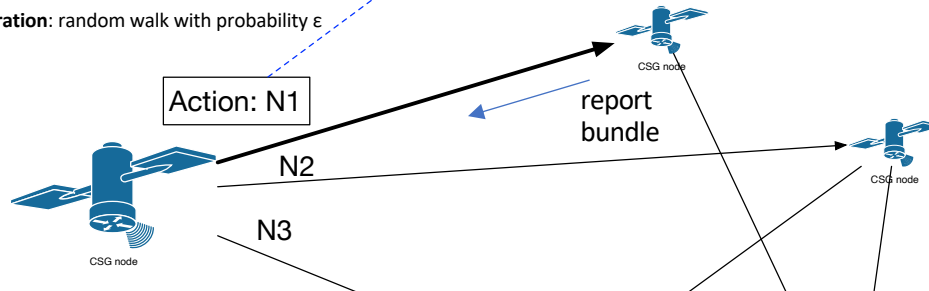


$$w(c_j, c_i) \leftarrow w(c_j, c_i) + \eta\delta ; j = 1, \dots, n; i \neq j$$

$$w^k(g, c_i) \leftarrow w^k(g, c_i) - \eta\delta ; k = 1, \dots, n$$

- i is the index of the selected action
- $\eta > 0$ is the learning rate
- δ is the cost advantage of the action
- Parallel inhibitory synapses k
- Cost = predicted path delay in the original CSG

Exploration: random walk with probability ϵ



CSG Method Improvements



1. Cost advantage based on the minimum cost for all actions
2. Cap on synapse strength updates
3. CNC pre-training
4. Multi-objective routing

Notes:

- Routing based on loss becomes relevant when best-effort CLAs are used
- Minimum delay and minimum loss may be contradictory routing optimization objectives

Multi-Objective Routing

Agent i , action j , destination d , cost C is given by:

- Delay
$$T_{i,d} = T_{i,j} + T_{j,d} + D_{i,d} \tag{1}$$

$$C = T_{i,d}$$

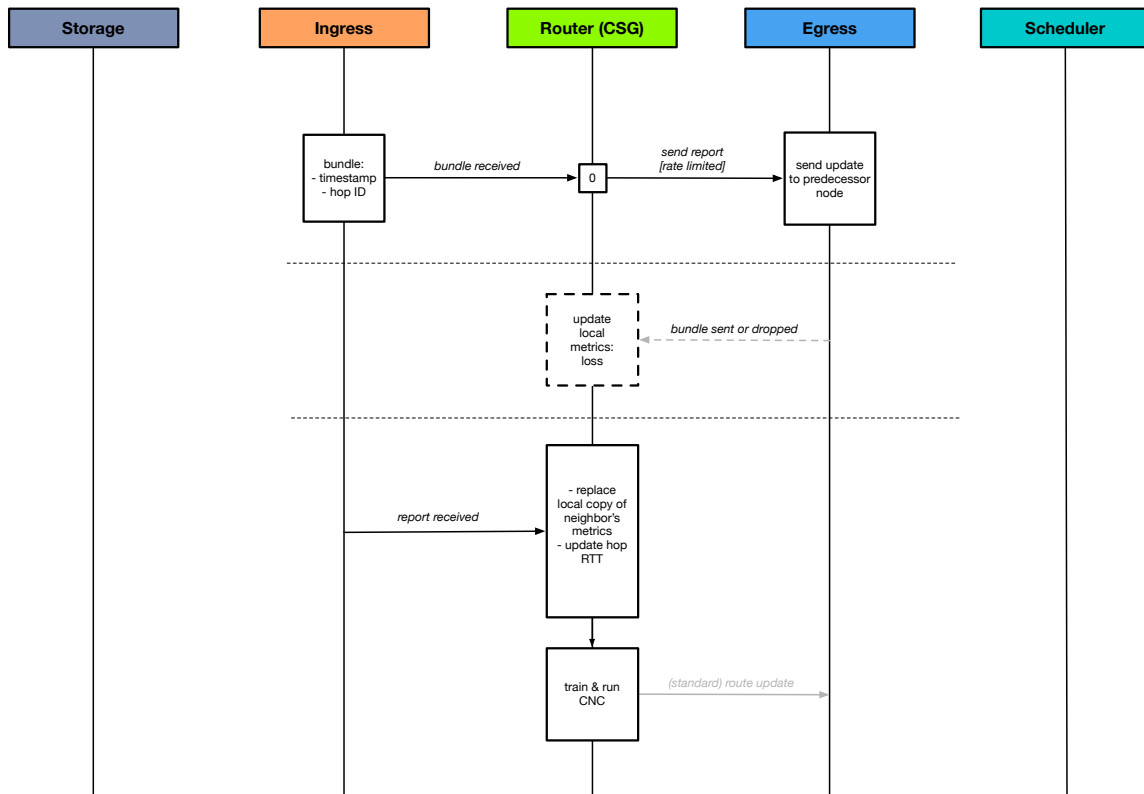
- Loss
$$P_{i,d} = 1 - (1 - P_{i,j})(1 - P_{j,d}) \tag{2}$$

$$C = \frac{1}{1 - P_{i,d}}$$

- Delay-loss
$$C = \frac{T_{i,d}}{1 - P_{i,d}} \tag{3}$$

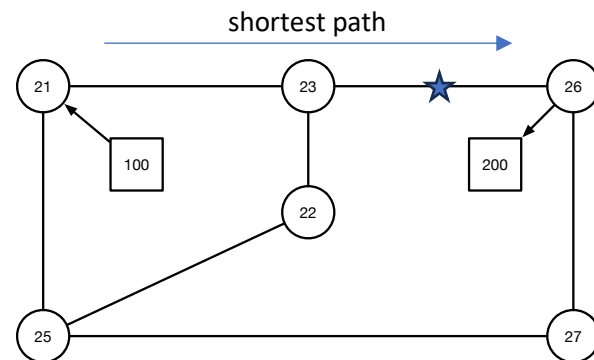
CSG Implementation for HDTN

- High-Rate DTN (HDTN) provides an implementation of DTN protocols for modern hardware platforms
- C++ and open-source libraries (Boost, OMQ, OpenSSL, etc.)
- Modular design
- CSG router module implemented



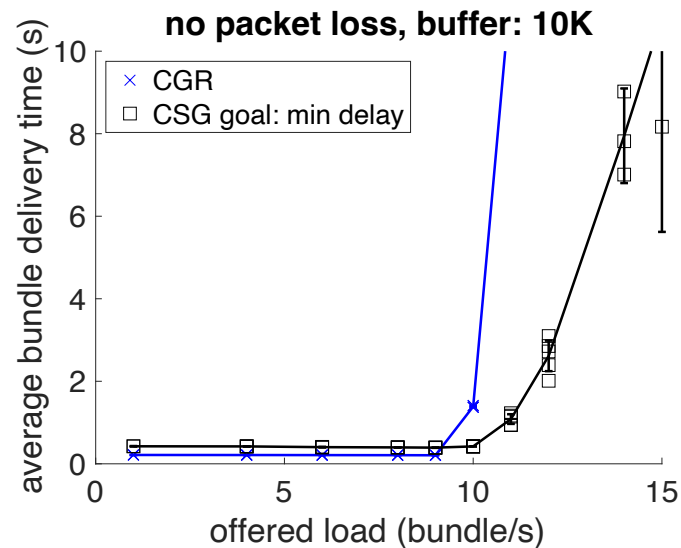
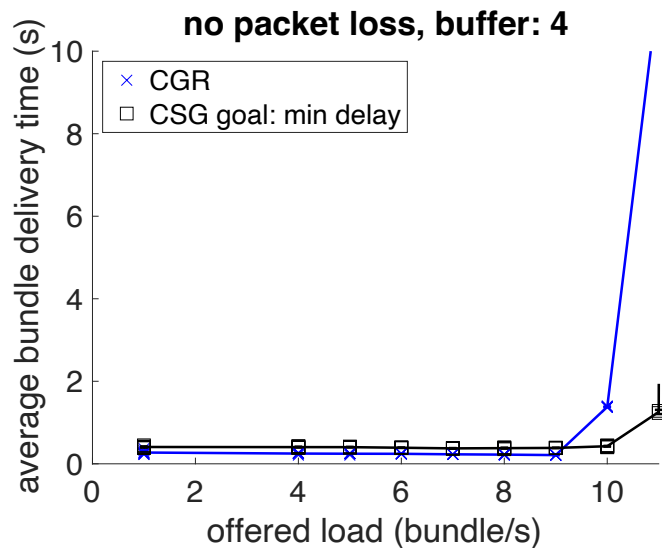
Experimental Evaluation

- Six R220 servers each equipped with six Ethernet ports
- Test flow:
 - *bpgen-async*: node 100 (running on node 21)
 - *bpsink-async*: node 200 (running on node 26)
- Links:
 - CAT-5 twister pair
 - 100 ms OWLT (propagation delay)
- Shortest path
 - 4 hops
 - 23-26 affected by loss



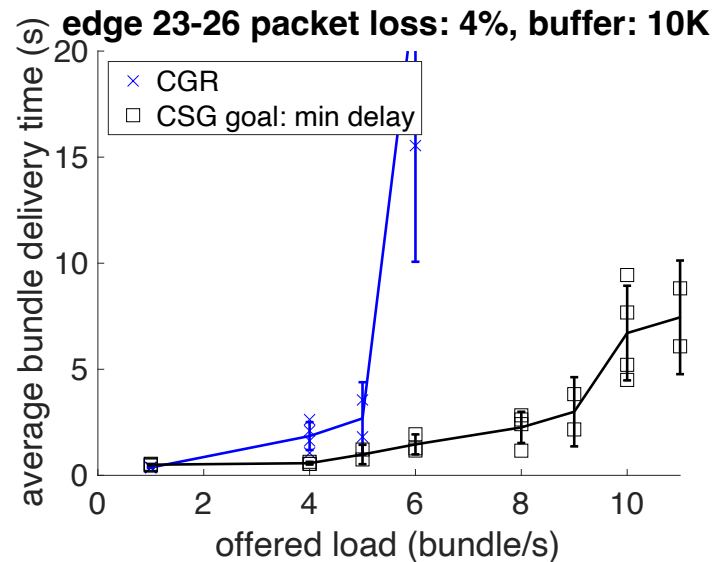
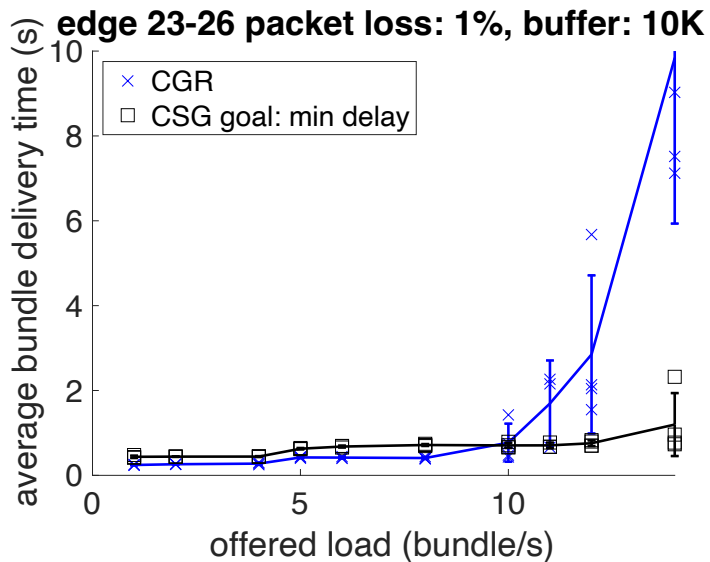
<i>HDTN parameters</i>	
udpRateBps	8×10^9 bps
maxNumberOfBundlesInPipeline	10^4
maxSumOfBundleBytesInPipeline	10^8 bytes
numRxCircularBufferBytesPerElement	65535 bytes
maxIngressBundleWaitOnEgressMilliseconds	100 ms
<i>CSG parameters</i>	
Exponential Moving Average factor (α)	0.1
Random walk probability (ϵ)	0.1
Learning factor (η)	0.01
CNC execution rate limit per destination (τ^{-1})	1
Max. path length	16

Min. Delay as Routing Goal (1)



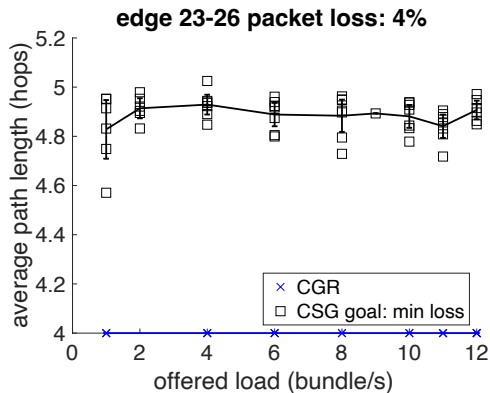
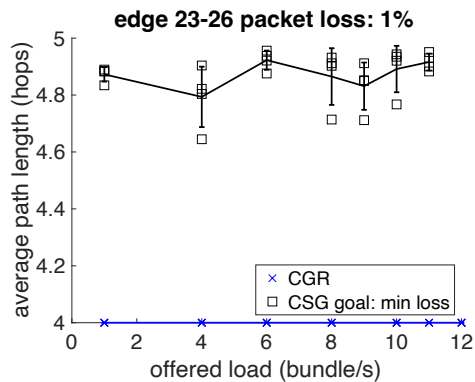
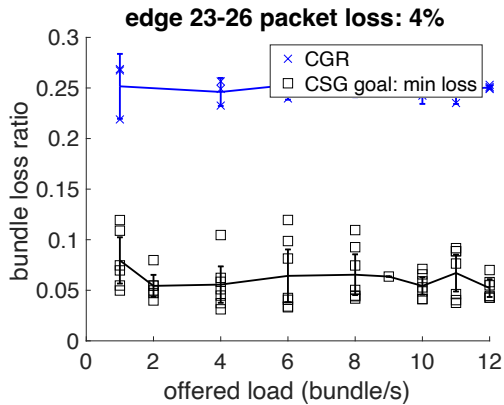
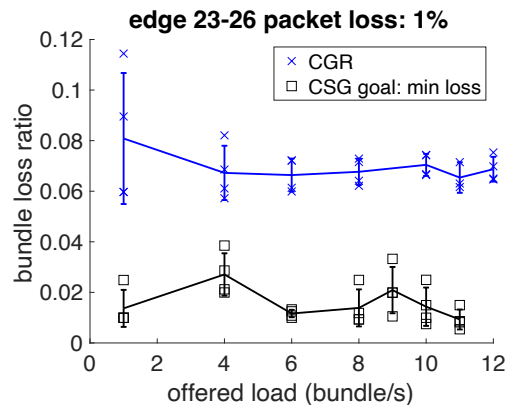
- Impact of (UDP) CLA's buffer sizes (HDTN parameter)
- CSG performs slightly worse of low loads because exploration may involve the use of suboptimal routes

Min. Delay as Routing Goal (2)



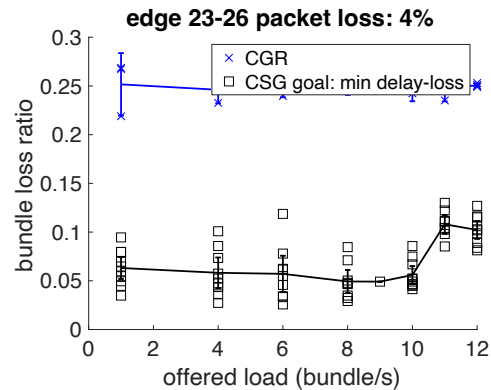
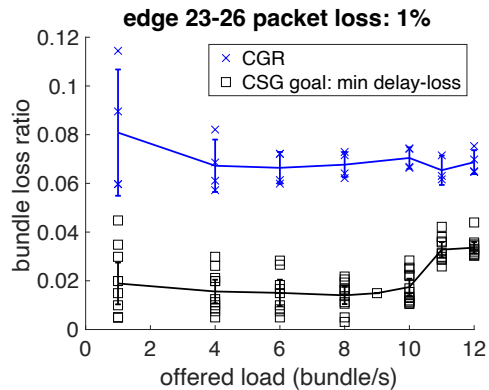
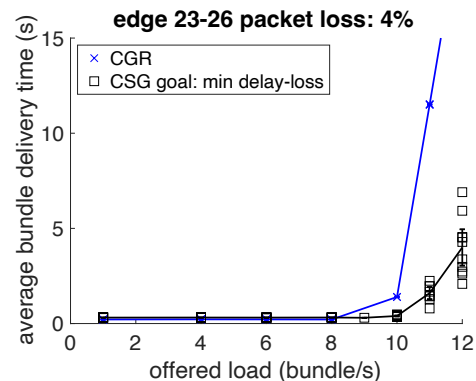
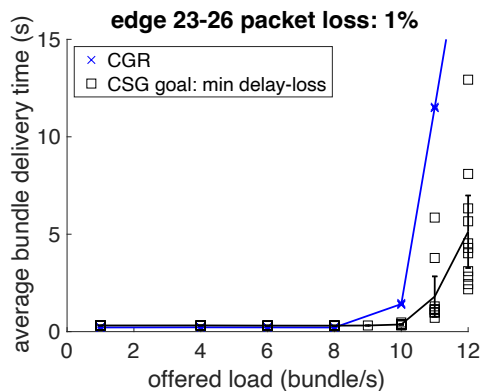
- CLA: *tcpcl_v3*
- Packet losses extend the average 23-26 hop bundle delivery time

Min. Loss as Routing Goal



- Best-effort CLA (UDP)
- Min. loss routing is approximately equivalent to max throughput routing

Delay-Loss as Routing Goal



Conclusion

- Enhanced the CSG algorithm for faster convergence and improved optimality
- Developed a dedicated CSG routing module for HDTN implementation
- Empirical experiments confirmed the efficacy of adaptive routing with the CSG, showing better performance than CGR for heavy traffic loads
- This work opens up future advancements and practical applications